

# Electrodynamics Vector Analysis Part 1

### Vector

- Tensors of rank 1
- They have direction as well as magnitude.
- Examples : Displacement, Velocity, Acceleration, Force, Momentum

## **Vector Operations**

• Four vector operations : Addition and three kinds of multiplication

1. <u>Addition of two vectors</u> : Place the tail of B at the head of A; the sum, A+B, is the vector from the tail of A to the head of B.

- Addition is commutative: A+B = B+A
- To subtract a vector, add its opposite:  $\mathbf{A} \mathbf{B} = \mathbf{A} + (-\mathbf{B})$



#### 2. Multiplication by a Scalar:

- Multiplication of a vector by a positive scalar **a** multiplies the magnitude but leaves the direction unchanged.
- If **a** is negative, the direction is reversed.
- Scalar multiplication is distributive:  $\mathbf{a}(\mathbf{A}+\mathbf{B}) = \mathbf{a}\mathbf{A} + \mathbf{a}\mathbf{B}$

#### 3. Dot product of two vectors

- If A and B are two vectors then A.B = AB cos θ; Where θ is the angle they form when placed tail to tail.
- Note that **A.B** is itself scalar ( so the name scalar product ).
- The dot product is commutative : A.B = B.A
- The dot product is distributive, **A**.(**B**+**C**) = **A**.**B** + **A**.**C**



- If the two vectors are parallel, then **A.B** = **AB**
- In particular, for any vector A,  $\mathbf{A} \cdot \mathbf{A} = A^2$
- If A and B are perpendicular, then A.B = 0

#### 4. Cross product of two vectors

- The cross product of two vectors is defined by  $\mathbf{A} \times \mathbf{B} = \mathbf{A} \mathbf{B} \operatorname{Sin} \boldsymbol{\theta} \mathbf{n}$
- Right hand rule : let your fingers point in the direction of the first vector and curl around (via the smaller angle) towards the second; then your thumb indicates the direction of n
- Note that A×B is itself a vector ( hence the name vector product ).
- Cross product is distributive,  $\mathbf{A} \times (\mathbf{B} + \mathbf{C}) = (\mathbf{A} \times \mathbf{B}) + (\mathbf{A} \times \mathbf{C}) \hat{\mathbf{n}} \hat{\mathbf{n}}$
- But not commutative;  $(\mathbf{B} \times \mathbf{A}) = -(\mathbf{A} \times \mathbf{B})$
- Geometrically, [A×B] is the area of the parallelogram generated by A and B.



• If two vectors are parallel, their cross product is Zero. In particular,  $A \times A = 0$  for any vector **A** 

## Vector Resolution

• The splitting of a single vector into two or more vectors in different directions which together produce a similar effect as is produced by a single vector itself. The vectors formed after splitting are called components vectors.



Vector Algebra : Component Form

**ENTRI** 

$$\mathbf{A} = A_x \,\widehat{x} + A_y \,\,\widehat{y} + A_z \,\widehat{z}$$

- The numbers  $A_x$ ,  $A_y$  and  $A_z$  are the components of A
- We can now reformulate each of the four vector operations as a rule for manipulating components ;

$$\begin{aligned} \mathbf{A} + \mathbf{B} &= (A_x \ \hat{x} + A_y \ \hat{y} + A_z \ \mathsf{Z}) + (B_x \ \hat{x} + B_y \ \hat{y} + B_z \ \hat{z}) \\ &= (A_x + B_x) \ \hat{x} + (A_y + B_y) \ \hat{y} \ + (A_z + B_z) \ \hat{z} \end{aligned}$$

• Rule (i) : To add vectors, add like components.

$$\mathbf{aA}=(\mathbf{a}A_x)\widehat{x}$$
 + (a  $A_y$ ) $\widehat{y}$  + (a $A_z$ ) $\widehat{z}$ 

- Rule (ii) : To multiply with a scalar, multiply each component
- Because,  $\hat{x}$ ,  $\hat{y}$  and  $\hat{z}$  are mutually perpendicular unit vectors,

$$\widehat{x} \cdot \widehat{x} = \widehat{y} \cdot \widehat{y} = \widehat{z} \cdot \widehat{z} = 1$$
  $\widehat{x} \cdot \widehat{y} = \cdot \widehat{x} \cdot \widehat{z} = \widehat{y} \cdot \widehat{z} = 0$ 

Accordingly,  $\mathbf{A}.\mathbf{B} = (A_x \ \hat{x} + A_y \ \hat{y} + A_z \ \hat{z})$ . ( $B_x \ \hat{x} + B_y \ \hat{y} + B_z \ \hat{z}$ )

$$= A_x B_x + A_y B_y + A_z B_z$$

- Rule (iii) : To calculate the dot product, multiply like components, and add
- In particular **A.**  $A = A_x^2 + A_y^2 + A_z^2$

So 
$$A = \sqrt{=A_x^2 + A_y^2 + A_z^2}$$
  
 $\hat{x} \times \hat{x} = \hat{Y} \times \hat{Y} = \hat{z} \times \hat{z} = 0$   
 $\hat{x} \times \hat{Y} = -\hat{Y} \times \hat{x} = \hat{z}$   
 $\hat{Y} \times \hat{z} = -\hat{z} \times \hat{Y} = \hat{x}$   
 $\hat{z} \times \hat{x} = -\hat{x} \times \hat{z} = \hat{Y}$   
 $A \times B = (A_x \hat{x} + A_y \hat{y} + A_z \hat{z}) \times (B_x \hat{x} + B_y \hat{y} + B_z \hat{z})$ 

This can be find using determinant

T

$$\mathbf{A} \times \mathbf{B} = \begin{vmatrix} \hat{x} & \hat{Y} & \hat{z} \\ Ax & Ay & Az \\ Bx & By & Bz \end{vmatrix}$$
$$= (A_y B_z - A_z B_y) \hat{x} + (A_z B_x - A_x B_z) \hat{Y} + (A_x B_y - A_y B_x) \hat{z}$$

• Rule (iv); To calculate the cross product, form the determinant whose first row is  $\hat{x}$ ,  $\hat{y}$ ,  $\hat{z}$  whose second row is A in component from and third row is B



#### **Problems**

1. Find the angle between the face diagonals of a cube of side 1



The face diagonals A and B are

 $\mathbf{A} = \mathbf{1} \ \widehat{\boldsymbol{x}} + \mathbf{0} \ \widehat{\mathbf{Y}} + \mathbf{1} \ \widehat{\boldsymbol{z}} \qquad \qquad \mathbf{B} = \mathbf{0} \ \widehat{\boldsymbol{x}} + \mathbf{1} \ \widehat{\mathbf{Y}} + \mathbf{1} \ \widehat{\boldsymbol{z}}$ 

So in component form

A.B = 1.0 + 0.1 + 1.1 = 1

On other hand, in "abstract " form,

A.B = AB 
$$\cos \theta = \sqrt{2} \sqrt{2} \cos \theta = 2 \cos \theta$$

Therefore  $\cos \theta = \frac{1}{2}$  or  $\theta = 60^{\circ}$ 

 $\hat{z} \ \hat{y}$ 

x